



DTN for Maritime and Underwater Sensor Networks

Diego Merani, Alessandro Berni NATO Undersea Research Centre, La Spezia IT (NURC)

Ricardo Martins Faculty of Engineering of the University of Porto (FEUP)

DTNRG session - IETF 83

Paris, 25-30 March 2012

Applications of underwater communications

Persistent monitoring sensor networks

- Security applications
- Environmental applications
- Pollution (oil spill, radioactivity)
- Ocean sampling networks
- Environmental monitoring Climate change
- Undersea exploration
- **Disaster prevention**
- Assisted navigation
- Coordination in swarms of AUVs
- Distributed tactical surveillance and tracking
- Mine reconnaissance













Underwater acoustic communications

- Acoustic communication is the foundational technology to interconnect nodes in the underwater domain
- Design of underwater communication protocols is affected by:
 Propagation delay
 - sound propagation in water is 1500 m/s, five orders of magnitude higher than EM
 - Time varying multipath and fading
 - □ Noise (ambient, biological, man-made)
 - Doppler distortion
 - Available acoustic bandwidth
 - □ High power medium absorption at high frequencies (>50 kHz)
 - Energy constraints
 - Low duty-cycle operations







Examples of acoustic modem performances



WHOI Micromodem

- □ Operational range: up to 1500 m
- nominal acoustic bitrate: up to 80 bps (FSK), up to 5400 bps (PSK)
- operational frequency band: 15kHz -25kHz - 28 kHz

Evologics 18/34

- □ operational range: up to 4500 m;
- nominal acoustic bitrate: up to 13.8 kbps
- operational frequency band: 18kHz -34kHz

Evologics 8/16

- □ operational range: up to 8000m;
- nominal acoustic bitrate: up to 6,9 kbps
- operational frequency band: 8kHz 16kHz

Objectives of our work

- Evaluate suitability of Delay/Disruption Tolerant Networking (DTN) to create networks composed of heterogeneous links (radio and acoustic)
- Develop of open-source software communications framework (Underwater Convergence Layer – UCL) to abstract the access to acoustic modems of several vendors

Joint effort of NURC and the Faculty of Engineering of Universidade do Porto (Portugal)



Initial bench tests

Software Architecture



Software modules

Platform Access and Abstraction (PAA) Module

- logging relevant messages and performance statistics to files and to the system console
- configuring and performing bi-directional communication with serial port devices and TCP/IP sockets
- □ support for threading and concurrency

Data Link (DL) Module

- □ delivering and receiving frames
- maintaining a list of reachable nodes
- advertising the local node

Modem Driver

- □ services requests to transmit data.
- sends notifications to other modules

Network Module

- exposes an interface to send and receive data in the form of packets
- □ implements transparent compression and decompression
- performs fragmentation and reassembly

ECL Client

- □ interacts with the local DTN2 ECL
- maintains a list of links that are presently open
- parses, validates and generates DTN ECL compliant XML messages
- uses the ECL XML Schema for communication with the local DTN daemon
- □ informs DTN about acoustic links available within range

Field tests

three fixed bottom-moored acoustic nodes

positioned to form a triangle with side length in the order of 1 km (positioned at 15, 21, 30 m depth);

one fixed acoustic node mounted on a buoy

positioned at 13 m depth, repositionable to vary the topology of fixed nodes

three hybrid (acoustic + RF) mobile nodes

- equipped with acoustic modem (at variable depth) and IEEE 802.11n wireless interface
- one mounted on Research Vessel Leonardo, the other two mounted on rigid-hulled inflatable boats (RHIBs)









Initial results from field testing

- The principal objectives of the field testing were demonstrate advanced network functionalities
 - □ application of DTN concepts to the maritime domain
 - in a heterogeneous context comprising underwater nodes communicating acoustically and surface nodes communicating with radio frequency
- During the field testing we were able to verify that the UCL operated according to the specifications
- A performance issue was observed with denser deployments (6 acoustic nodes)
 - the contention of the shared underwater channel became evident through a very high number of collisions.
 - The cause of this issue was tracked down to an implementation flaw that allowed for node advertisements to bypass the MAC module

Current work

Improve the existing API

- support additional acoustic modems
- □ support for multiple MAC protocols

Experiment aggressive optimizations to the DTN bundle protocol

- Reduce header/protocol overhead
- □ Test a DTN-lite implementation for the maritime environment

Support for dynamic routing

New protocols specifically adapted to persistent surveillance scenarios, swarm networking etc.

Interoperable communication between heterogeneous underwater clusters

- $\Box \text{ Acoustic} \leftrightarrow \mathsf{RF} \leftrightarrow \mathsf{Acoustic}$
- □ Platform-independent, DTN enabled middleware
- DTN-enabled communication module for MOOS-IvP (Mission Oriented Operating Suite - Interval Programming)

MOOS-IvP is a software suite to provide autonomy on robotic platforms, in particular autonomous marine vehicles

Semi-permanent testbed at NURC



Testbed scenario

- 4 Underwater fixed acoustic nodes, connected with underwater cables to NURC
- □ up to x AUV with Acomms (e-folaga)
- □ 2 RHIBs with Acomms, connected via RF wireless with NURC
- □ 1 gateway buoy with Acomms, connected via RF wireless with NURC
- □ 2 USV with Acomms, connected via RF wireless with NURC

Vision for 2012 (REP12 AUV)



Conclusions

- We have demonstrated that DTN and UCL can be used to transparently and reliably interconnect "traditional" IP-based and acoustic networks
- DTN is suited for use in maritime hybrid networks, for mission critical transactions where data must be delivered reliably across a set of highly heterogeneous links in order to reach the intended destination.
- If used with current acoustic modem technologies, DTN requires adaptation to cope with the limited available bandwidth



Thank you for your attention



PARTNERING FOR MARITIME INNOVATION

{merani,berni}@nurc.nato.int rasm@fe.up.pt