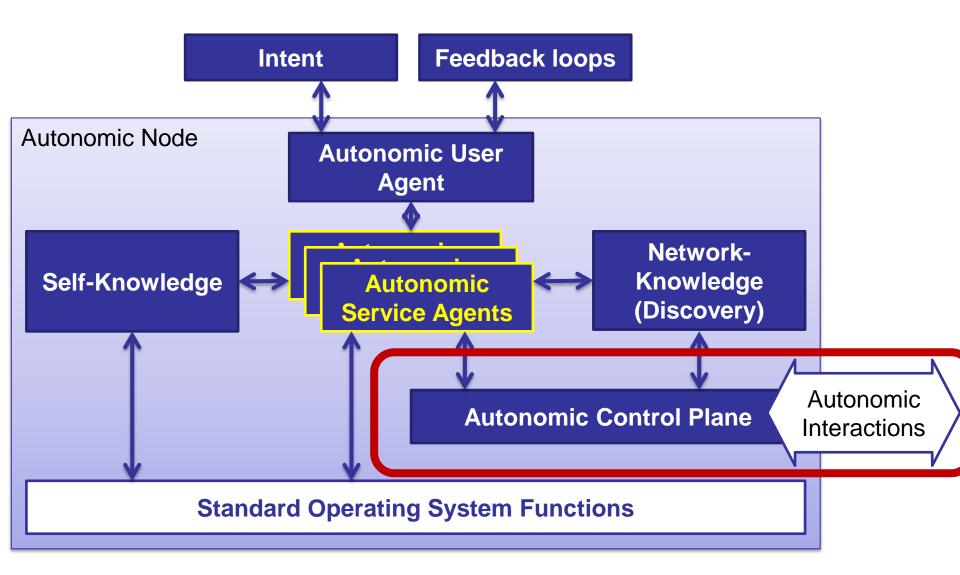
An Autonomic Control Plane

draft-behringer-anima-autonomic-control-plane-03.txt

93rd IETF, 20 July 2015
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Reference Model of an Autonomic Node



The Autonomic Control Plane

- Definition: The conjunction of protocols and interactions between autonomic service agents on nodes and registrars.
 - Includes: Discovery, negotiation, messaging, etc.
- Four options (from RFC7575):
 - Out of band: On a separate DCN
 - In a configured overlay network (VPN)
 - Inband: Like today's control plane protocols
 - In a self-managing overlay network (VPN)



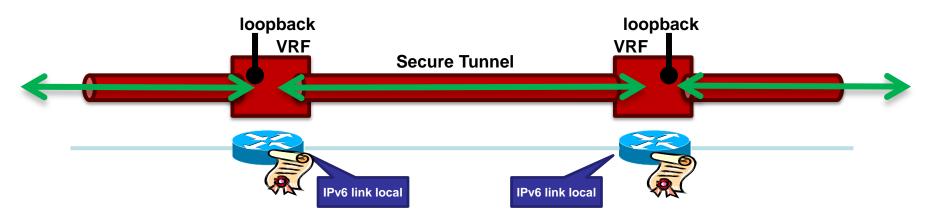
Changes from -02 to -03

- More focus on supporting autonomic functions
- Two key use case categories:
 - Autonomic functions
 - Traditional protocols, for co-existence
- Two options:
 - A virtually separated ACP
 - A data plane based ACP
- Requirements

Requirements (new section)

- The ACP SHOULD provide robust connectivity
- The ACP MUST have a separate address space from the data plane
- The ACP MUST use autonomically managed address space.
- The ACP MUST be generic
- The ACP MUST provide security

Autonomic Control Plane – Self-Managing Overlay Network



- Routing inside the ACP to distribute loopbacks
- Automatic
- Routing protocol must be scalable and light-weight

Properties of the Autonomic Control Plane (self-managing overlay)

- Self-Creating
- Self-Managing
- Self-Healing
- Self-Optimising
- Self-Protecting

The Autonomic Control Plane is autonomic itself!

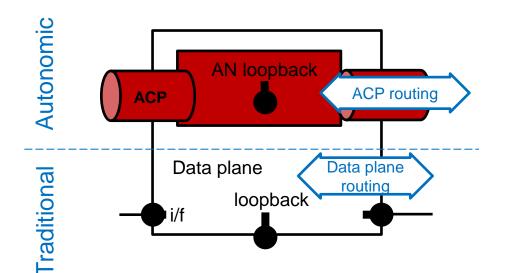
Use Cases: (see also draft-eckert-anima-stable-connectivity)

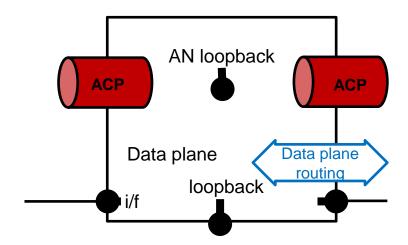
- Bootstrapping an un-configured network
- Virtual Out Of Band Channel
 - ACP not dependent on configuration, addressing, routing



Virtually separate ACP

Data plane based ACP

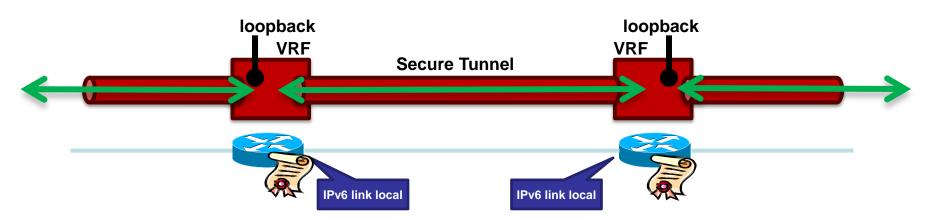




- Addressing, routing: Independent
- AN loopback managed autonomically
- ACP tunnel use IPv6 link local
- AN communication between AN loopbacks only

- Single addressing, routing
- AN loopback managed autonomically
- Tunnel use IPv6 link local
- AN communication between AN loopbacks only

Hop by Hop?



- Some function must be hop by hop
 - Bootstrap of a network, for example
- Robustness higher with hop by hop
 - No dependency on configured or autonomic addressing
- But, functions must also work unicast between any two nodes.

Discussion

- Is the scope of the document right?
 - Two options: virtually separated and data plane ACP
- Is the structure of the document right?
- What are open issues / concerns?
- Is this ready for WG adoption?