A day in the life of an autonomic function

P. Peloso, L. Ciavaglia

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Motivations

Autonomics can improve network operations
Operators need unified management functions to use autonomics and gain confidence in it.

Common management functions of AF bring
- **trust in Autonomic Functions behavior**
- **capacity to control Autonomic Functions**
- **conflict avoidance mechanisms**

Management of Autonomic Functions 3 phases

Installation | To dynamically install ASA to Nodes.

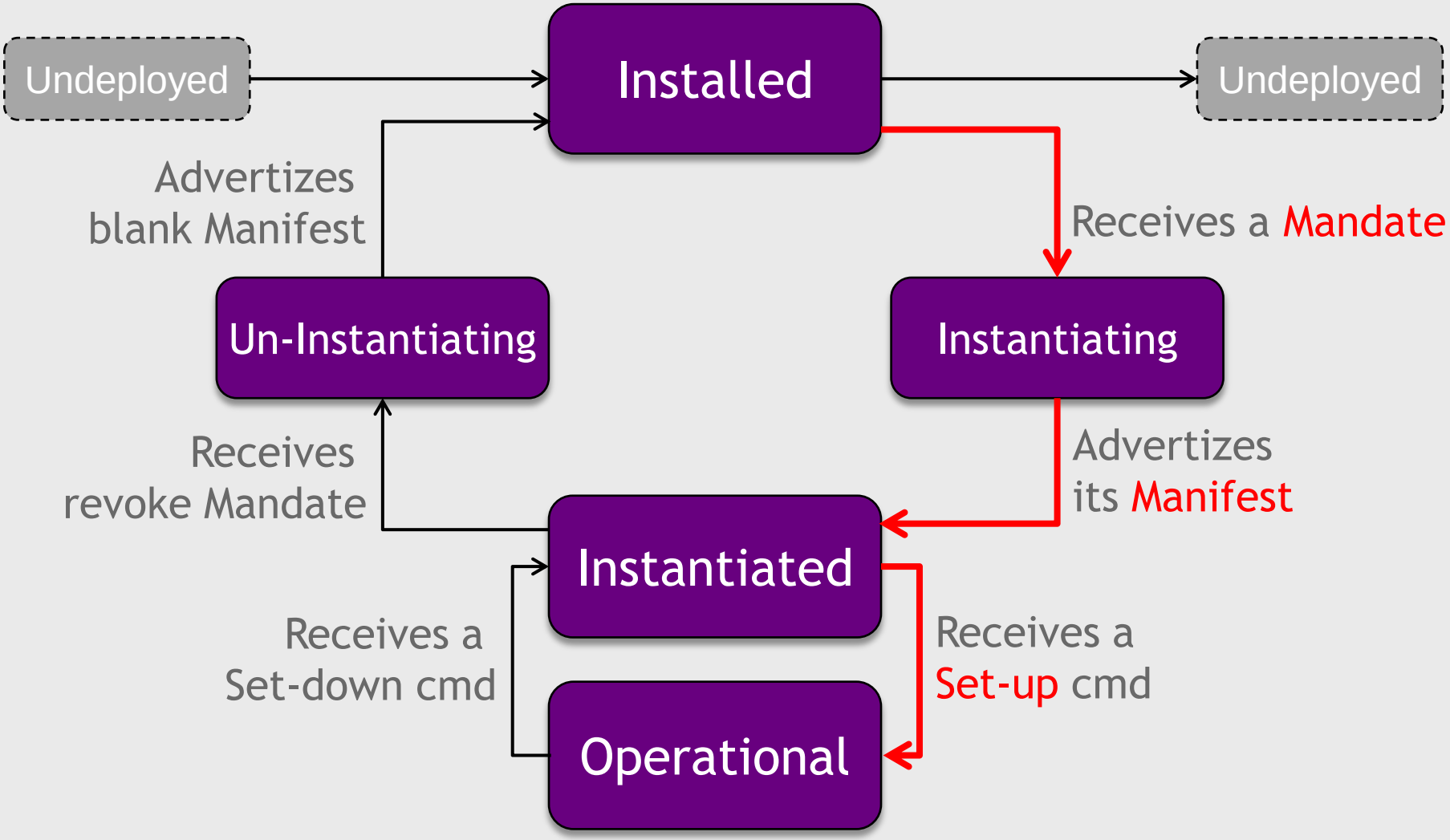
Instantiation | To allocate the network resources to be managed by ASA.
To organize ASA in ASA domains.

Operation | To control the running of ASA.
To avoid conflicts between ASAs.
To share knowledge between ASAs.

Focus of today

ASA life-cycle

3 states + 2 transit ones



ASA Interactions

The Life-Cycle shows that:

Entities pertaining to the
Control of Autonomic Function are
interacting with the **ASAs**
and serving **all** ASAs

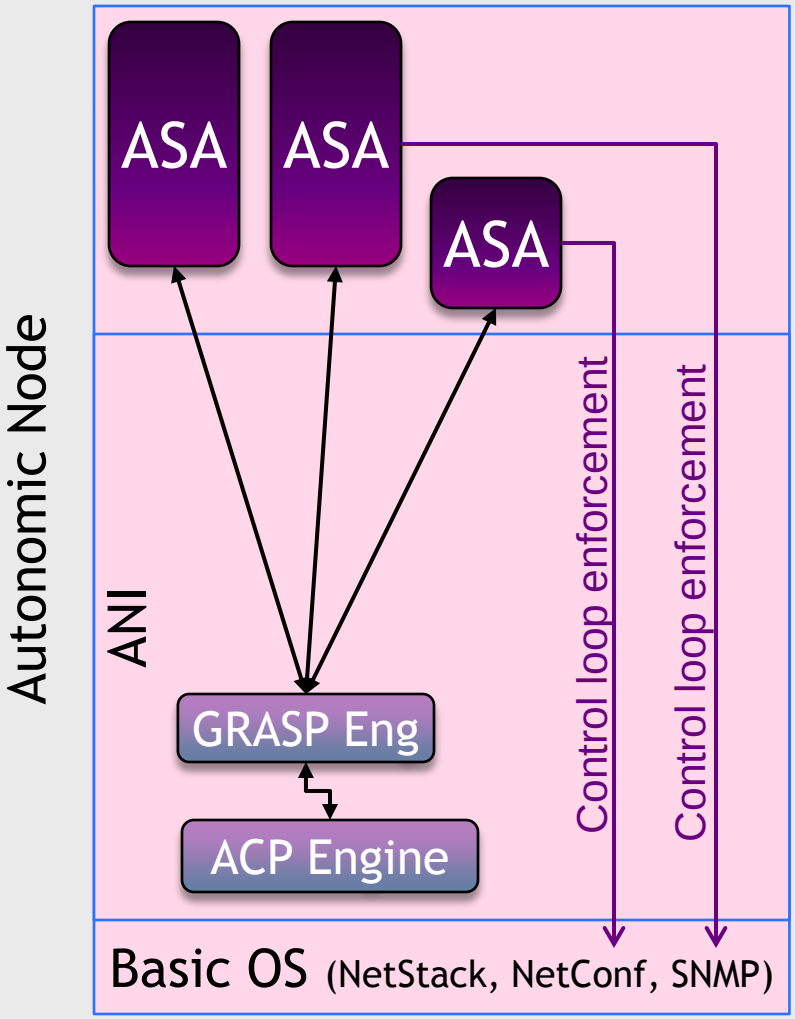
AF Mgt Function

Coordination Function

Info sharing Function

What is needed in the ANIMA ecosystem?

Autonomic Networking Infrastructure — The toolbox



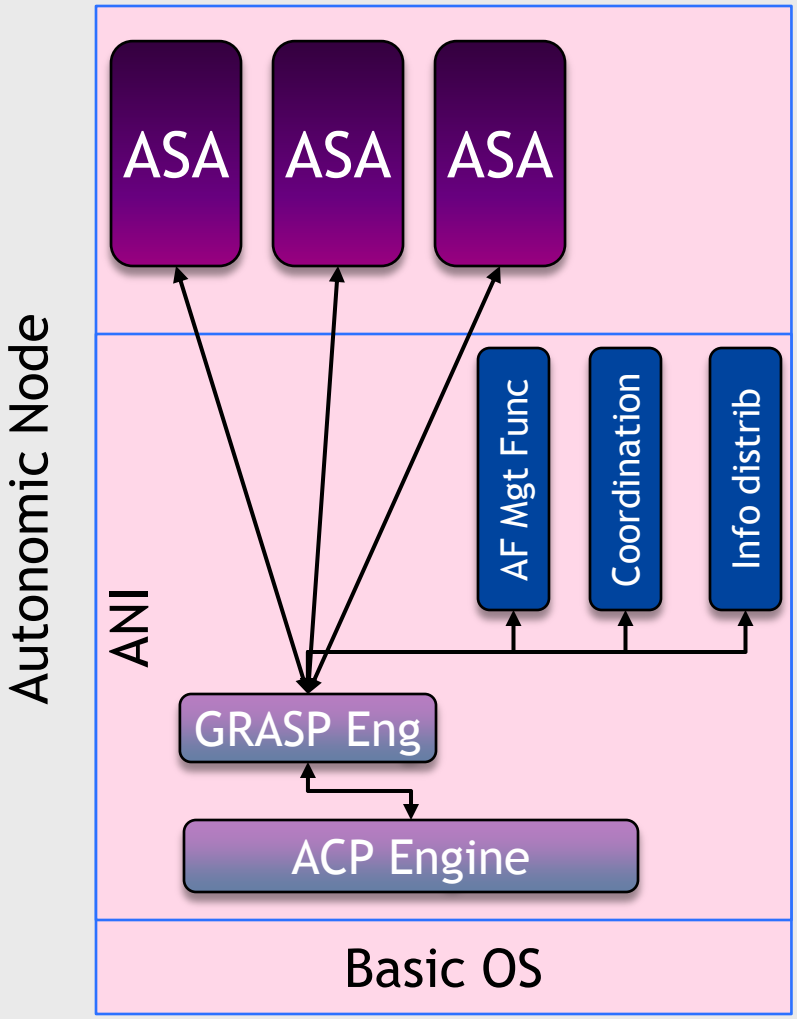
Current ANIMA picture

- GRASP preferably uses ACP
- ASA use GRASP signaling in-between them
- ASA monitor the equipment and modify its state directly using either NetConf, SNMP, call to Basic OS API…

Legend

Protocol engine

Autonomic Networking Infrastructure — The toolbox



Simplest option to control ASAs:

- Same as before
- Plus use GRASP signaling between ASAs and AF Control Agents (Coordination, AF Mgt, Info Distribution)
- Hence multiple type of GRASP clients

Legend

Protocol engine

ANI function (serving ASAs)

Nota

The functions controlling autonomic functions NEED NOT being instantiated in each Node

Actually there even likely being instantiated in servers part of the ACP but not on network equipments like routers or switches.

Minimal control of ASA

Control when it runs
(and how it runs)

Know what it does to the network

Decide which equipments are under the ASA control
(Or vice-versa which ASAs control an equipment)

Control when an ASA runs

NEED

- On request Start and Stop the execution of ASA

SOLUTION

- Send a START command
- Send a STOP command

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IN ANIMA

- Add to GRASP imperative commands type of message

Know what an ASA does to the network

NEED

- Know which network resources are modified by ASA control loop
- Know which network resources are monitored by ASA control loop

SOLUTION

- Disclose an ASA Manifest at ASA bootstrap time

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SOLUTION

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IN ANIMA

- Disclose Manifest with GRASP Discovery messages

Decide which ASA control which equipment

NEED

- Give instructions to ASA during bootstrapping

SOLUTION

- Send a Mandate to ASA before end of bootstrap

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SOLUTION

- Send a Mandate to ASA before end of bootstrap

IN ANIMA

- Specify Intent formats compatible with Mandate and identify proper message in GRASP to convey Intent

Conclusion

Minimal control of ASA

Control when it runs — Start/Stop

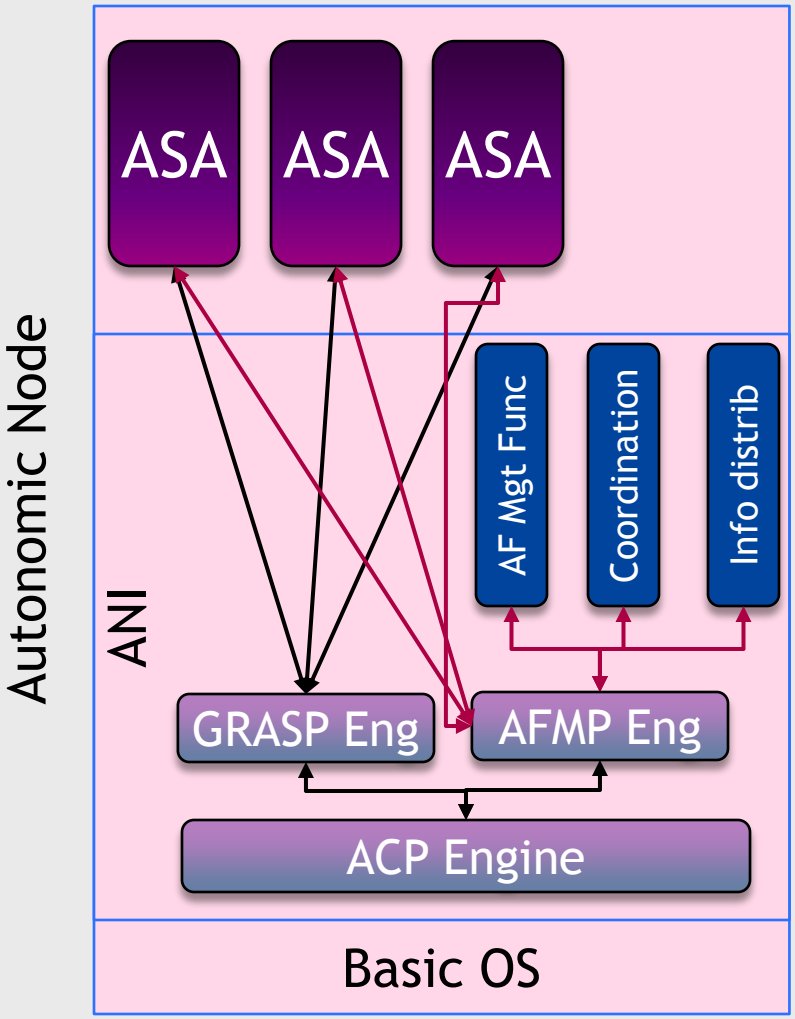
Know what it does to the network — Manifest

Decide which equipments are under the ASA control — Mandate

Conclusion

Can we design a solution that oversees the operators trust in it ?

Appendix



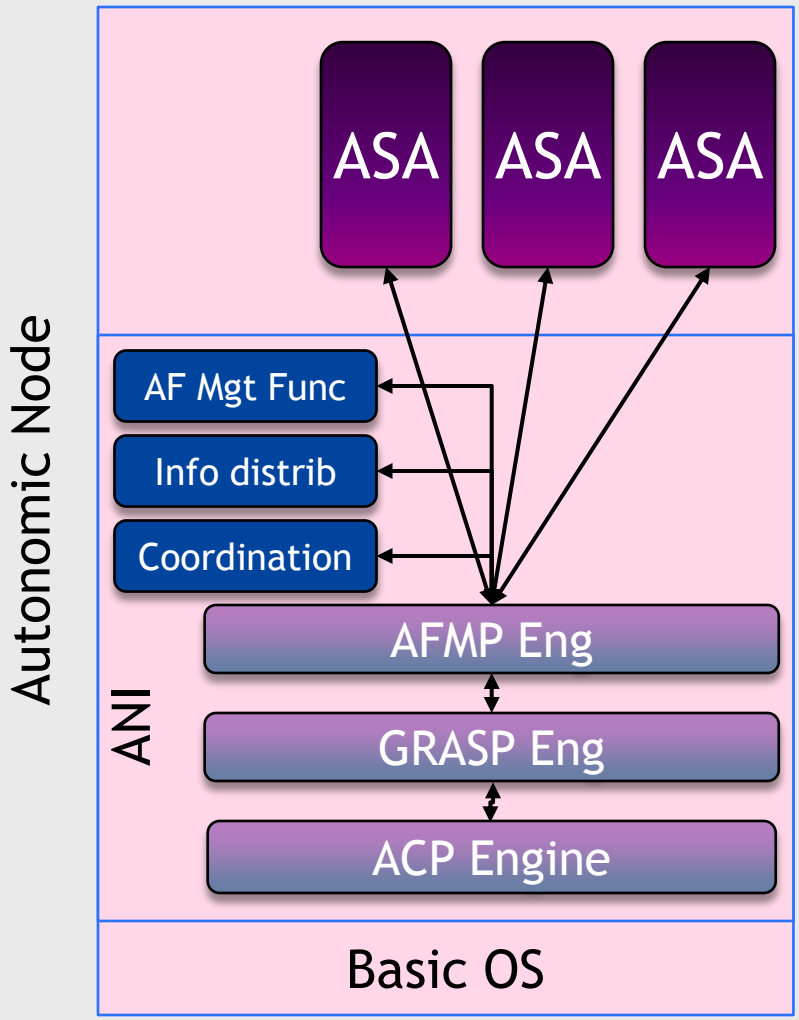
Other option

- Segmenting between ASA-ASA and ASA-ANI function

Legend

Protocol engine

ANI function (serving ASAs)



In case GRASP should absolutely not care about semantics of what is carried and roles of its clients

Legend

Protocol engine

ANI function (serving ASAs)

Deployment examples of AF