

# A day in the life of an autonomic function

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IETF 95<sup>th</sup>

`draft-peloso-anima-autonomic-function-01`

# Motivations

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**Autonomics can improve network operations  
Operators need unified management functions to  
use autonomics and gain confidence in it.**

**Common management functions of AF bring**

- trust in Autonomic Functions behavior**
- capacity to control Autonomic Functions**
- conflict avoidance mechanisms**

## Changes in 01

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- Enhanced split between ANIMA next phase items and current items
- Documented requested extensions to GRASP
- Identified items for Reference Model

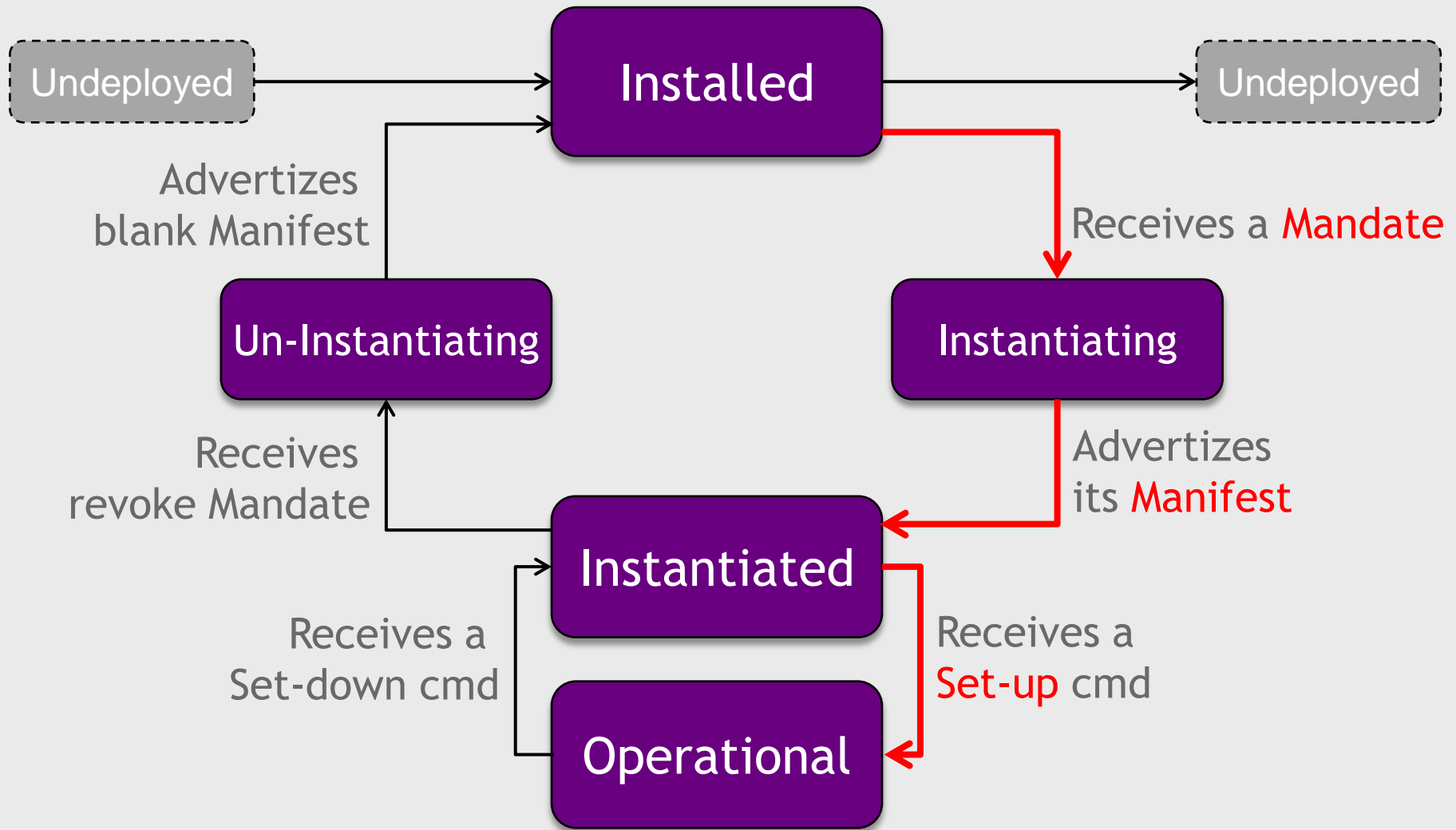
# Controlling ASAs - Their life-cycle

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To be kept in mind for future work

# ASA life-cycle

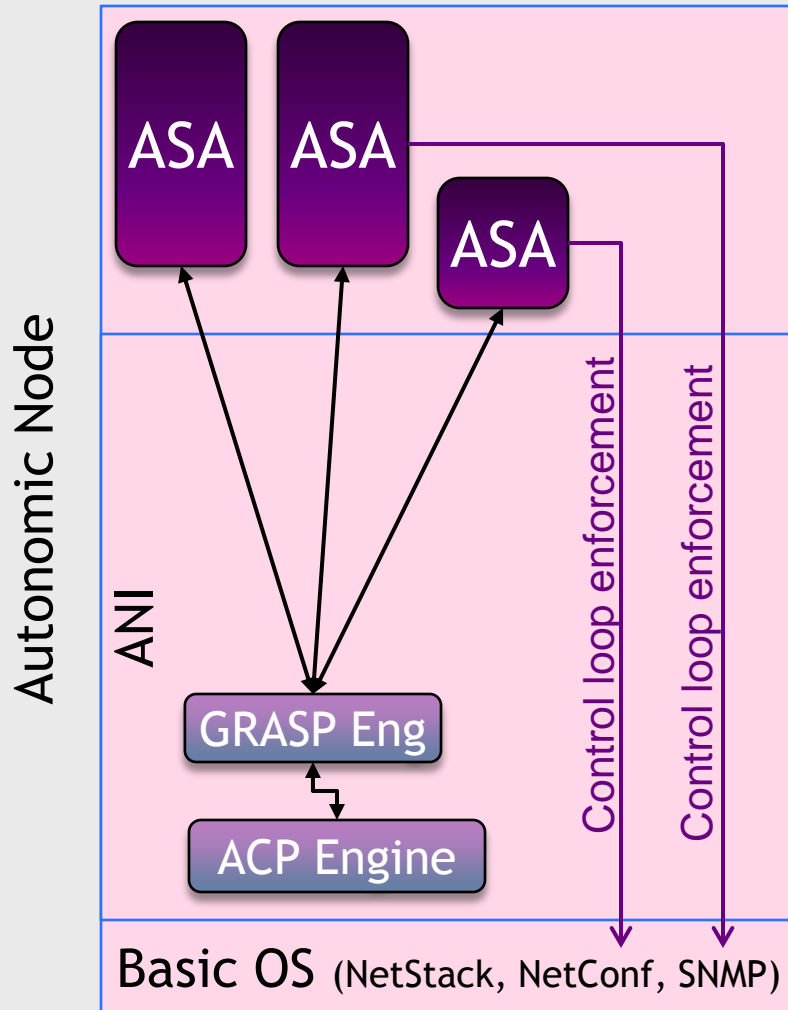
3 states + 2 transit ones



# Controlling ASAs - Minimal control

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Filling holes in current solution



## Current ANIMA picture

- GRASP preferably uses ACP
- ASA use GRASP signaling in-between them
- ASA monitor the equipment and modify its state directly using either NetConf, SNMP, call to Basic OS API...

## Legend

Protocol engine

# Minimal control of ASA

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**Control when it runs**  
(and how it runs)

**Know what it does to the network**

~~**Decide which equipments are under the ASA control**  
(Or vice-versa which ASAs control an equipment)~~



# Control when an ASA runs

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## NEED

- On request Start and Stop the execution of ASA

## SOLUTION

- Send a START command
- Send a STOP command

# Control when an ASA runs

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## NEED

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## SOLUTION

- Send a START command
- Send a STOP command

## IN ANIMA

- Add to GRASP imperative commands type of message

- Suggested form:

```
imperative-message =  
    [M_IMPERATIVE, session-  
    id, initiator,  
    objective]
```

# Know what an ASA does to the network

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## NEED

- Know which network resources are modified by ASA control loop
- Know which network resources are monitored by ASA control loop

## SOLUTION

- Disclose an ASA Manifest at ASA bootstrap time

# Know what an ASA does to the network

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## NEED

- Know which network resources are modified by ASA control loop
- Know which network resources are monitored by ASA control loop

## SOLUTION

- Disclose an ASA Manifest at ASA bootstrap time

## IN ANIMA

- Disclose Manifest with GRASP Discovery messages
- 2 options:
  - Whole manifest disclosed in a single discovery message
  - Each manifest entry disclosed in an independent discovery message

WG/GRASP designers to provide guidance there

Control when it runs

**Start/Stop**

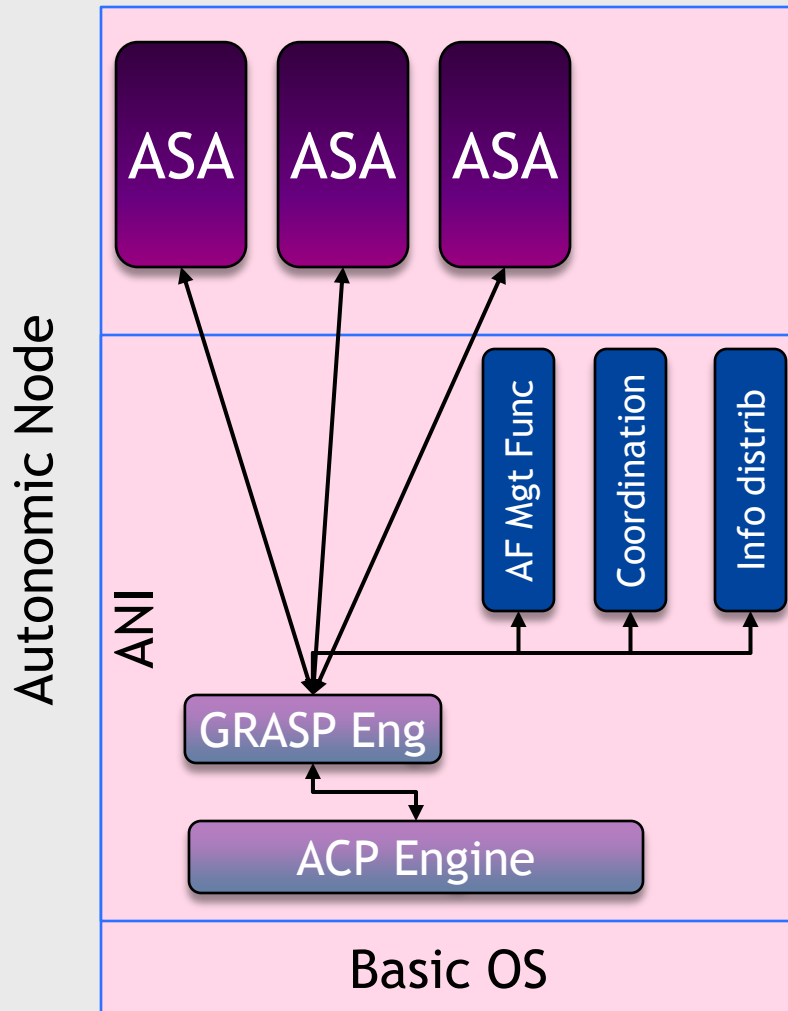
Know what it does to the network

**Manifest**

# Conclusion

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Can we design a solution that oversees the operators trust in it ?



Simplest option to control ASAs:

- **Same as before**
- Plus use GRASP signaling between ASAs and AF Control Agents (Coordination, AF Mgt, Info Distribution)
- Hence multiple type of GRASP clients

Legend

Protocol engine

ANI function  
(serving ASAs)